## CS70

# Discrete Probability 

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March 18, 2021

## Overview

(1) Probabilistic Models
(2) Probability Space
(3) Discrete Uniform Probability Space

## Probabilistic Models

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- sample space $\Omega$ : set of all all possible outcomes of an experiment.
- probability law: assigns to a set $A$ of possible outcomes (event) a nonnegative value $P(A)$ (probability of $A$ ) that encodes the knowledge about the likelihood of the elements of $A$.


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Sample space $\Omega$ :
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Sample point $\omega$ :
An element from the sample space.
Event:
A subset of the sample space.

## Probability Space

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The probability space is defined by the triple $(\Omega, \mathscr{A}, P)$ where $\Omega$ is the sample space, $\mathscr{A} \subseteq \Omega$ is the event space and $P$ is the probability function, satisfying the following axioms:

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- Additivity: any countable sequence of disjoint sets (mutually exclusive events) $E_{1}, E_{2}, \ldots$ satisfies

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\sum_{\omega \in \Omega} P(\omega)=P(\Omega)=1
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- If $A \subseteq B$, then $P(A) \leq P(B)$.


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For uniform spaces, computing probabilities is simply counting sample points.

## Problem Time!

